SPECIFICATIONS

Sensing elements	4 ultrasonic in TPA* configuration	
Operating range	1ft 5ft.	
Response time	2.0 seconds	
Relay output configuration	2 SPDT (form C)	
Relay contact rating	1A @ 24VDC120VAC	
Power indicator/no vehicle	Green LED	
Object in range	Flashing Green LED on each input, continuous LED on DETECT	
Supply Voltage	1224 VDC/VAC	
Operating current	60mA	
Dimensions	5.7"(145mm) x 3.6"(90mm) x 2.3"(57mm)	
Weight	0.6 lbs. (275g)	
Operating temperature	-40°C+85°C (-40°F+182°F)	
Housing	ABS	
Connection	10 position terminal block	
Mechanical protection	NEMA 4X	

Patent pending Triangular Planar Array

CAUTIONS AND WARNINGS

This product is an accessory or part of a system. Always read and follow the manufacturer's instructions for the equipment before connecting this product. Comply with all applicable codes and safety regulations. Failure to do so may result in damage, injury or death



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USVD-4X

ULTRASONIC VEHICLE DETECTOR PATENT PENDING



OPERATING INSTRUCTIONS

MATERIALS SUPPLIED

- · Operating Instructions
- USVD-4X

GENERAL DESCRIPTION

This device uses patent pending Triangular Planar Array (TPA) technology to reliably detect the presence of a vehicle in a wide variety of drive-thru applications including parking, access control, car wash, banking and fast food. Unlike a vehicle loop detector configuration that requires the installation of a loop in the pavement, the USVD may be simply mounted on a post or order box and aimed at the location of the vehicle when in position to perform a transaction or place an order. Also, unlike other technologies, the USVD does not require any set up or functional adjustments, other than simply installing and aiming. The USVD greatly reduces the cost associated with installation of vehicle detection capabilities compared to loop detectors for these types of applications.

The USVD requires 12-24VDC/VAC and provides a form "C" set or relay contacts indicating vehicle presence.

Utilizing TPA technology, the detection head consists of 4 ultrasonic transducers that connect to a remotely mounted control board. The detection head "scans" the expected location for a vehicle and activates its output upon detection of a vehicle.

The USVD provides a 2.0 second response. A green indicator on the USVD control board flashes indicating power and no vehicle detection and continuous on indicating vehicle detection. Individual green indicators located near each

transducer connection flash when an echo from a surface 1-5ft. in front of the transducers is present.

The solid-state FAIL output is activated when a solid object, such as ice, is present preventing 1 or more transducers from vibrating.

WIRING

TERMINAL	CONNECTION
1	+V (12 to 24VAC/VDC)
2	-V (power supply common or VAC)
3	Relay 1 NC contact
4	Relay 1 common contact
5	Relay 1 NO contact
6	Relay 2 NC contact
7	Relay 2 common contact
8	Relay 2 NO contact
9	Fail - solid state output (open drain)
10	Spare

FUNCTION SETTINGS

The four switch settings control the operation of the relays as indicated in the following tables.

RELAY 2 (auxiliary output)				
FUNCTION	1	2		
CONSTANT	OFF	OFF		
PULSE ON ENTRY	ON	OFF		
PULSE ON EXIT	OFF	ON		
PULSE ON BOTH	ON	ON		

RELAY DELAY OPTIONS (R1 and R2)				
FUNCTION	3	4		
NO DELAY	OFF	OFF		
1 SECOND	ON	OFF		
2 SECONDS	OFF	ON		
4 SECONDS	ON	ON		

APPLICATION INFORMATION

Single lane:

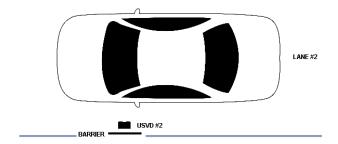
Install the USVD at 22-24" above the height of the pavement surface where the vehicle is located. Align the USVD perpendicular to the side of the vehicle. Connect power and outputs as required by the control system.

Rotate the detector assembly front panel if necessary to allow vehicle direction as shown.



Multiple lanes:

For installations with multiple lanes, it may be necessary to place a barrier up to 24" x 24" behind the USVD to prevent echo from other units from being reflected into the detector.



LANE #1

USVD #1

INSTALLATION

Turn off power before connecting the USVD. See wiring information for connections.

The USVD should be mounted at 22-24" above the height of the pavement surface where the vehicle is located. . Align the USVD perpendicular to the side of the vehicle. Connect power and outputs as required by the control system.

The relay contacts are listed in the non-presence condition, i.e. no vehicle is detected.